Shuangning Li





Dyadic Reinforcement Learning

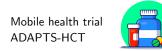
Li, Shuangning, Lluis Salvat Niell, Sung Won Choi, Inbal Nahum-Shani, Guy Shani, and Susan Murphy. arXiv preprint arXiv:2308.07843 (2023).



Goal: enhance medication adherence

Adolescent Cancer Patient





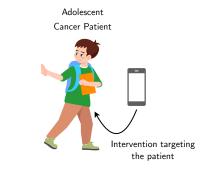
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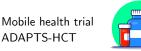
Reinforcement learning algorithm:



Decides whether/when to deliver interventions that target the cancer patient







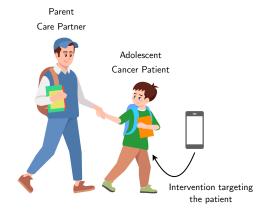
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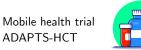
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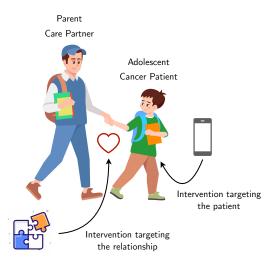


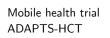
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that target the cancer patient 🛛 👷



Decides whether/when to deliver interventions 0~ that target the relationship ()



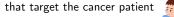


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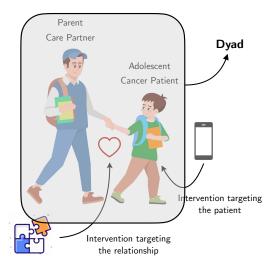
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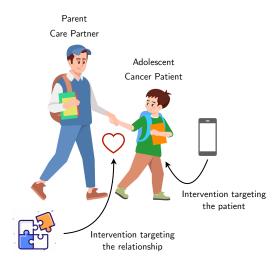
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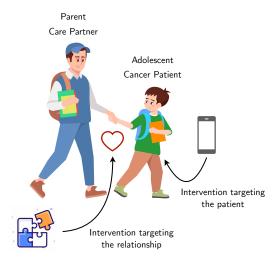




Intervention targeting the relationship:

- $\boldsymbol{\diamondsuit}$ Weekly prompt for the dyad to play a joint game.
- ♦ A puzzle-solving game.
- The game lasts throughout the week.
- Once the adolescent takes the medication, it triggers a clue for the parent.
- If they win the game, a donation is made to their favorite charity.

Smart medication boxes with sensors!



Notation

State

Weekly state S^{weekly}: weekly measurements of the quality of the dyadic relationship.
 Daily state S^{daily}: various daily measurements related to adolescents and their parents, such as their step count, sleep duration or mood.

Action

Weekly action A^{weekly}: whether to send the weekly intervention to encourage the adolescent and their parents to participate in the joint game.
 Daily action A^{daily}: whether to send the daily reminder to the adolescent.

Reward R_{t} whether the adolescent cancer patient takes the medication.

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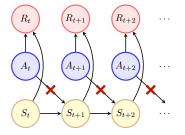
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Let's focus on the daily state and action temporarily!



✦ Assumes that there is no delayed effect of actions.

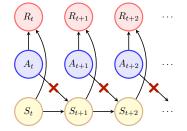






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 "Burden effect" in mobile health studies: Users feel burdened or disengage when receiving too many messages.









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Nonstationarity especially within a week.







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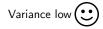
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Bandit algorithm:





RL Algorithm?



Consider RL algorithms that take into account full non-stationarity and delayed effect. Treat the problem as a finite-horizon reinforcement learning problem.

E.g., one can run the RLSVI (randomized least-squares value iteration) algorithm.

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- In ADAPTS-HCT, each dyad will be involved in the trial for 15 weeks \approx 100 days. Need to maintain 100 different *Q*-functions for each day in the trial.
 - Mobile health data is usually very noisy. \rightarrow Hard to capture delayed effects.

RL Algorithm?

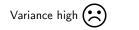


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Full RL algorithm:





Assumes that the impact of actions does not extend to the following **day**.

Bandit algorithm

Low Variance High Bias Allows for delayed effects.



Full RL algorithm

High Variance Low Bias

Assumes that the impact of actions does not extend to the following **day**.

Assumes that the impact of actions does not extend to the following **week**.



Allows for delayed effects.



Full RL algorithm

Bandit algorithm

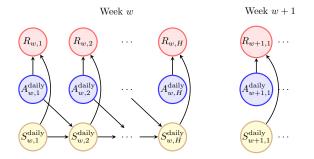
Dyadic RL algorithm

Low Variance High Bias Find a balance between variance and bias

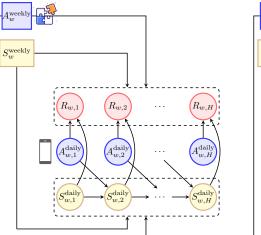
High Variance Low Bias

Domain science tells us that:

- ✓ Weeks exhibit similar structures.
- \checkmark There is a high level of noise in state transitions and rewards.



The algorithm makes the assumption that the impact of actions does not extend to the following **week**. This assumption is to address the challenge of high noise.



Week w

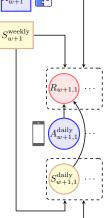
Week w + 1

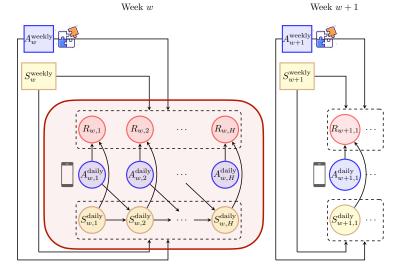
Two types of interventions:

 \clubsuit Daily reminder

✤ Weekly game prompt

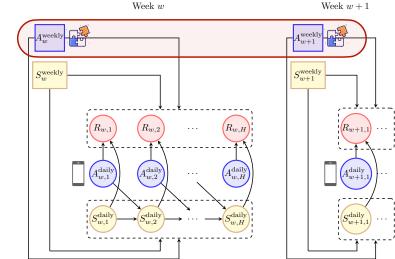
Weekly game prompt is expected to impact the dyad throughout the entire week.





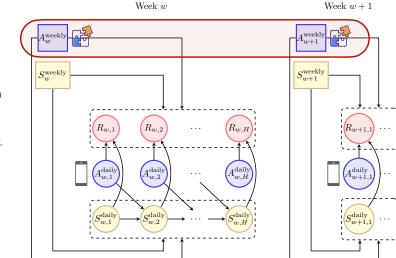
Daily action:

- **★** Finite-horizon problem with H = 7.
- ★ We choose to use RLSVI
 because of its Bayesian nature.
 → Helps with interpretability.



Weekly action:

- \star Contextual bandit problem.
- ★ We choose to use Thompson Sampling because of its Bayesian nature.
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Weekly action:

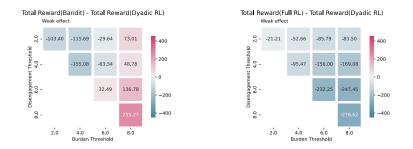
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Reward?

- ★ Sum of realized rewards: too noisy!
- ★ Estimate of the *Q*-function on day 1.

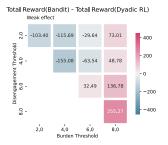
Theoretically, we establish a regret bound for the dyadic RL algorithm within a tabular setting.

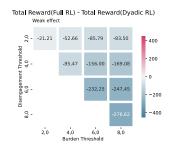
Empirically, we demonstrate the dyadic RL algorithm's performance through simulation studies on both toy scenarios and on a realistic test bed constructed from data collected in a mobile health study.



Simulation Test Bed

Total Reward(baseline) - Total Reward(Dyadic RL): green means dyadic RL is performing better

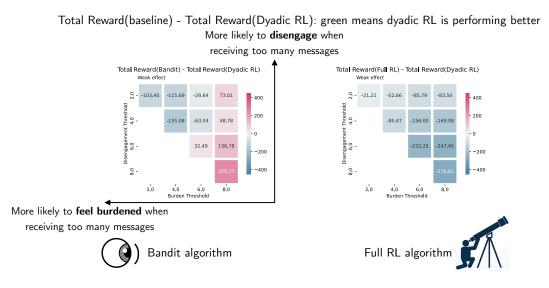








Simulation Test Bed





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https://lsn235711.github.io/

